# RJSSP38/6 Series

# INSTRUCTION FOR USERS

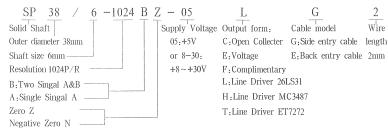
# OF ROTARY ENCODER

**\*\*CAUTIONS:** Users of rotary encoder should observe following instructions before they touch the encoder.

PRECAUTIONS FOR HANDLING

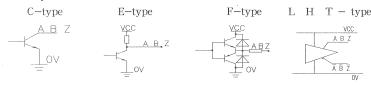
- 1. Isolate the encoder from shock and vibration.
- 2. Keep the encoder away from dust, oil, water, high or low temperature and corrosive materials. These situations may cause the damage of the encoder and a personal injury.
- 3. Any modification of the encoder is prohibited. A modified encoder is not a subject to the warranty.

# **\*Definition Of Models and types**



#### **\*Number of Pulses**

#### **\*Output Circuit**



#### **\*Output Waveforms**

Open collector, Voltage output, Complimentary Line driver



The waveforms from viewed from the coupled plate and clockwise rotation.

Waveforms ratio:

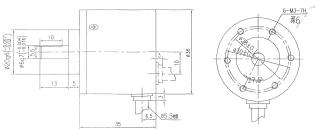
 $X1 + X2 = 0.5T \pm 0.1T$ 

 $X2 + X3 = 0.5T \pm 0.1T$ 

Phase shift:  $X n \ge 0.2T$  n=1,2,3,4 (T=360/N N:The rotation of the shaft output number of pulses)

Signal Width of Z:  $Tz=1T\pm0.3T$ 

#### **\*External dimension (Unit in mm)**



### **\*Features and Application**

Small size, low cost General model
High resolution max.3600P/R
Wide ranging power source, DC+5V Or DC+8~+30V
Industrial application, Measuring instruments.

#### **\*Electrical Spec**

Output type	L, H-type	C, E, F - type	T-type		
Supply Voltage	+5V ±5%	+5V or +8~30V	+5V or +8~30V		
Current Consumption	≤150mA	≤60mA	≤150mA		
Load current	20mA	30mA	20mA		
Voltage Output(VH)	≥2.5V	≥VCC*70%	≥VCC*70%		
Voltage Output(VL)	≤0.5V	≤0.5V	≤0.5V		
Rising / falling time	≤100ns	≤1us	≤100ns		
Max.Response Frequency	150KHz	150KHz	150KHz		

#### **\*\*Mechanical Spec**

#### **\*Environmental Spec**

 $1000 \text{m/s}^2$ , 6ms

-10℃ ~ +70℃

-20°C ~ +80°C ≤RH80% IP50°

 $100 \text{m/s}^2, 10 \sim 200 \text{Hz}$ 

≤20N	Shock resistance		
≤10N	Vibration resistan		
≤1X10 <sup>-3</sup> N.m	Operating Temp:		
6000r/min	Storage Temp:		
20g/cm <sup>2</sup>	Ambient Humidi		
1X10 <sup>4</sup> rad/s <sup>2</sup>	Protection class		
Approx 0.1Kg			
	≤10N ≤1X10 <sup>-3</sup> N.m 6000r/min 20g/cm <sup>2</sup> 1X10 <sup>4</sup> rad/s <sup>2</sup>		

#### **\*Connection Table**

Wire colour	Red	Black	Green	White	Yellow	Brown	Grey	Orange	Shield
L,H,T Type	+V	0V	SIG A	SIG B	SIG Z	SIG Ā	SIG B	SIG Z	G
C,E,F Type	+ V	0V	SIG A	SIG B	SIG Z				G

#### **\*INSTRUCTION FOR INSTALLATION**

#### The Mechanical Spec.

- 1. The encoder shaft is not wanted the rigidity to link by the shaft with user, Please use elasticity to connection the board Socket
- 2. The encoder should be fixed on the motor axis, and attention to coaxial degree requirement of encoder and motor axis.
- 3. During the installation, Please pay attention to the shaft load that the ware was permitted.

## The Electrical Spec.

- 1. The supply voltage should be kept within the required range. it may cause the damage of the encoder.
- 2.A shielded cable should be used for encoder output connec tion. The cable should be isolate from AC power lines to avoid motor interference.
- 3. The mistake distribution can damage the internal, when the distribution, The wirings of the rotary encoder should be connected according to color codes of wires and electrical connections.
- 4.Please not wind encoder output line together or the same pipeline transmits with the motive force thread etc. We should also unsuitably put in the nearby use of distributor.

#### **\*Quality assurance**

If the encoder does not function properly within 18 months of the delivering date due its poor quality, it will be repaired or replaced by the producer for free only when customer has strictly followed the regulations for maintenance and operation.